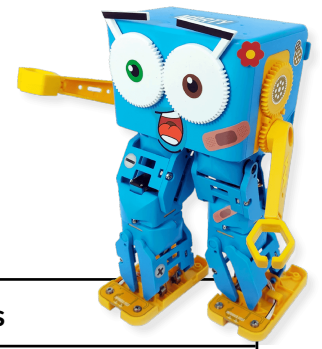


Marty the Robot Tech Specs

9 DoF biped with all metal geared smart servos

ROS compatible via WiFi, USB or onboard Raspberry Pi via expansion header



Hardware Features

Outputs	Sensors	Other Features
<ul style="list-style-type: none"> 9 x Individually controllable metal geared smart servo motors <ul style="list-style-type: none"> 3 per leg Both arms Eyebrow movement A full speaker for text-to-speech and playing music 2 x Ring of 12 individually programmable RGB LEDs 	<ul style="list-style-type: none"> 9 x Position and force sensing on each motor 2 x Ground contact sensor 2 x IR obstacle sensor Color sensor 3 axis accelerometer for motion and tilt sensing Optional: distance sensor, light sensor, noise sensor Camera and mic via raspberry pi 	<ul style="list-style-type: none"> 3200 mAh rechargeable battery, class packs come with 1 spare battery per robot and multiport charger Connect over BLE, WiFi or USB (python only) Auto power off Automatic motor jam and fall sensing and deactivation Raspberry Pi compatible 2 yr no quibble warranty

Interfaces

Unplugged	Controller / Sequencer	Jr Blocks	Blocks
<ul style="list-style-type: none"> Color tiles give instructions directly to Marty Screen free coding for ages 4+ 	<ul style="list-style-type: none"> Remote control to move Marty Then start sequencing to solve challenges 	<ul style="list-style-type: none"> Icon based blocks Top down Marty simulator Program movement, sound and lights Based on Scratch Jr 	<ul style="list-style-type: none"> Text based blocks Sensor data inputs Make custom movements, react to the environment... Based on Scratch

Sensor Dashboard	Python	Raspberry Pi	ROS2
	<pre> python3 -m pip install --user martypy import martypy # USB connection # Change "/dev/ttyUSB0" to "/dev/ttyUSB1" if you have 1 USB port you want to use # Comment "/dev/ttyUSB0" line out to use WiFi my_marty = martypy.Marty("usb") # WiFi connection # Comment "/dev/ttyUSB0" and change the IP address to your Marty's to use WiFi # my_marty = martypy.Marty("wifi", "192.168.0.1") my_marty.get_ready() my_marty.dance() for i in range(10): my_marty.sidestep(1,1,1, 2) my_marty.walk(100, 100, 2, 2, 2, 2, 2) my_marty.sidestep(1,1,1, 2) my_marty.walk(100, 100, 2, 2, 2, 2, 2) </pre>		
<ul style="list-style-type: none"> Capture data from any of Marty's sensors Use within blocks or export as csv 	<ul style="list-style-type: none"> MartyPy library provides easy access to all Marty's features Control multiple Martys from one script over WiFi! 	<ul style="list-style-type: none"> Make Marty fully autonomous! Use camera for onboard vision processing Run ROS onboard 	<ul style="list-style-type: none"> Python node over WiFi, USB or UART ROS2 Wrappers in progress now